

Effective from Session: 2022	2-23						
Course Code	EE-513	Title of the Course	Advance Power Electronics	L	Т	Р	С
Year	1 <sup>st</sup>	Semester	1 <sup>st</sup>	4	0	0	4
Pre-Requisite	None	Co-requisite	None				
Course Objectives	<ul> <li>Kno</li> <li>Use</li> <li>Kno</li> <li>Ide:</li> <li>Kno</li> </ul>	whedge and concept of of switching technique owledge and concept of ntify and apply concept owledge of synchronou	voltage source inverter. s/schemes and current source inverters. multilevel inverters, its applications and control of resonant converters. s rectifiers and matrix converters.				

	Course Outcomes
CO1	Know about the concepts of voltage source inverter
CO2	Identify and apply switching techniques/schemes and current source inverters
CO3	Know about concept of multilevel inverters, its applications and control.
CO4	Identify and apply concept of resonant converters
CO5	Know about synchronous rectifiers and matrix converters.

Unit No.	Title of the Unit	Content of Unit	Contact Hrs.	Mapped CO							
1	Switch-Mode Inverters	Basic concepts of voltage source inverter (VSI), current source inverters (CSI), single phase half bridge, full bridge and three phase bridge inverters.	8	CO1							
2	8	CO2									
3	Multi-Level Inverters	Need for multilevel inverters, Types, three level, five level inverter operation and analysis. Applications of multilevel inverters and control.	8	CO3							
4	Resonant Converters	Basic resonant circuit concepts, Load resonant converters, series and parallel, resonant switch converters – Zero voltage switching (ZVS), Zero current switching (ZCS), comparison of resonant converters.	8	CO4							
5	Miscellaneous Converters	Multilevel converters topologies: Cascaded, NPC, Flying Capacitor MLI, Synchronous rectifiers, matrix converters,	8	CO5							
Referen	ce Books:										
1. Ned N	Aohan, "Power Electron	ics Converters, Applications, and Design" John Wiley (SEA), 3rd Ed 2014.									
2. M. H.	Rashid "Power Electro	nics" PHI Learning									
3. G. K.	. Dubey, "Power Semi-C	Conductor Controllers", Wiley Eastern, 2nd Edition, 2012.									
4. R W I	4. R W Erickson and D Maksimovic "Fundamental of Power Electronics" Springer, 2ndEdition.										
5. M.H.	5. M.H. Rashid, "Hand book of Power Electronics", 4th Edition,2013.										
e-Lear	ning Source:										

						С	ourse A	Articul	ation N	Aatrix:	(Mappi	ng of COs	s with PO	s and PSO	Os)			
PO- PSO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4	PSO5	PSO6
CO																		
CO1	3	2	2	1	1	3	3	1					1	2	2			
CO2	3	2	2	2	3	3	3						1	2	2			
CO3	3	2	2	1	1	3	3	1					1	2	1			
CO4	3	2	2	2	3	3	3						3	2	1			
CO5	3	3	3	3	3	3	2						2	3	1			



Effective from Session: 2022	2-23						
Course Code	EE-514	Title of the Course	Power Apparatus & System Modelling	L	Т	Р	С
Year	1 <sup>st</sup>	Semester	1 <sup>st</sup>	4	0	0	4
Pre-Requisite	None	Co-requisite	None				
Course Objectives	<ul> <li>To</li> <li>To</li> <li>To</li> <li>To</li> <li>To</li> </ul>	develop knowledge on p understand the fundame provide advanced know analyze governors for th evaluate the performanc	principles of modelling of synchronous generators ntal concepts of application of Parks transformation ledge and understanding about the models of transmission li nermal and hydro power plant re of different excitation systems	ne, tra	nsform	er and l	oad

	Course Outcomes
CO1	Understands the basic concept of modelling of synchronous generators
CO2	Apply Parks transformation technique
CO3	Understand different models of transmission line, transformer and load
CO4	Analyze governors for thermal and hydro power plant
CO5	Evaluate the performance of AC and DC excitation system

Unit No.	Title of the Unit	Content of Unit	Contact Hrs.	Mapped CO								
1	Synchronous Generator Modeling	Schematic diagram, equivalent circuit, Starting method, balanced operation, Park's transformation (dqo transformation)	8	CO1								
2	Dynamic Modeling of Synchronous Generator	Modeling of synchronous generator with damper windings; Synchronous Machine Parameters: operational and standard, Effect of Saturation on Synchronous Machine Modelling.	8	CO2								
3	Modelling of Excitation systems	Excitation system requirements, Types of Excitation system, Control and protective function of Excitation system, Modelling of various Excitation system, IEEE type various DC, AC and Static models.	8	CO3								
4	4 Prime Movers Modelling Steam turbine and Governing system: Various configurations of Steam turbine of fossil- fueled and nuclear units, Modelling of Steam turbine and its governing systems. Hydraulic turbine transfer function, linear and Non- linear turbine model, Modelling of Governors for Hydraulic turbine											
5	Modelling of Other Power System Components	Induction Motor, Synchronous Motor, Transformers, transmission lines, Static and Dynamic loads, Selected FACTS Controllers (SVC and TCSC).	8	CO5								
Referen	ce Books:											
<b>1.</b> A.A. ]	Foud& P.M. Anderson,	"Power System Stability and Control", Galgotia Press, New Delhi, 2014.										
<b>2.</b> L.P. S	Singh, "P.S. Analysis &	Dynamics", Wiley Eastern, Delhi, 2014										
<b>3.</b> P. Ku	ndur, "Power System St	ability and Control", Mc-Graw Hill, 2010										
4. K.R. Padiyar, "Power System Dynamics: Stability and Control", B.S. Publications, 2008												
e-Lear	e-Learning Source:											

						C	ourse A	Articul	ation N	Aatrix: (	Mappin	ng of COs	s with PO	s and PSC	Ds)			
PO- PSO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4	PSO5	PSO6
C01	3	2		1								3	3	2	3			
CO2	3	2						1				3	3	2	2			
CO3	3	1									2	3	3	2	3			
CO4	3	2									1	3	3	2	2			
CO5	3	2						1				3	3	2	3			



Effective from Session: 2022	2-23						
Course Code	EE-515	Title of the Course	Advance Power System Analysis	L	Т	Р	С
Year	1 <sup>st</sup>	Semester	1 <sup>st</sup>	4	0	0	4
Pre-Requisite	None	Co-requisite	None				
Course Objectives	Kno     Kno     Kno     Kno     Kno     Kno     Kno     Kno	whedge of graph theory whedge of algorithm of whedge of power flow s whedge of Contingency owledge of Modern ene	<ul> <li>bus admittance and impedance matrices</li> <li>bus impedance matrix and short circuit studies using three- solutions</li> <li>and security studies</li> <li>argy control Techniques</li> </ul>	phase	Impeda	nce ZBU	JS

	Course Outcomes
CO1	Solve the problem of graph theory, bus admittance and impedance matrices
CO2	Able to attain the knowledge of algorithm of bus impedance matrix and short circuit studies using three-phase Impedance $Z_{BUS}$
CO3	Able to solve the problems of power flow solutions
CO4	Having knowledge of Contingency and security studies
CO5	Having knowledge of Modern energy control Techniques

Unit No.	Title of the Unit	Content of Unit	Contact Hrs.	Mapped CO							
1	Introduction	System graph, loop, cut-set and incidence matrices; Algorithms for the formation of bus admittance and impedance matrices, Three-phase Admittance YBUS and Impedance ZBUS matrices;Optimal load flow	8	CO1							
2	2Power flow solutionsGauss-Seidel, Newton-Raphson, Approximation to Newton-Raphson Method, Line flow equations and Decoupled and Fast decoupled techniques.										
3	Fault Analysis	Symmetrical faults, Fault calculations using ZBUS, Unsymmetrical faults-Problems on various types of faults.	8	CO3							
4	Contingency and security studies	Factors affecting security, State transition diagram, Contingency analysis using network sensitivity method and AC power flow method.	8	CO4							
5	5 Modern energy control Techniques Modern energy control centres, Introduction to Supervisory Control and Data Acquisition in power systems(SCADA), benefit of SCADA, Remote terminal and connection, Human machine interface										
Referen	ce Books:										
1. G.W.	Stagg & A.H. Al-Abiad	, "Computer Methods in Power Systems", Mc-Graw Hill, 1998.									
2. Haadi	Sadat, "Power System	Analysis", Tata McGraw Hill, 2002									
3. M.A.	Pai, "Computer Technic	ues in Power System Analysis", Tata McGraw Hill, 2014									
4. D. P.	4. D. P. Kothari and I. J. Nagrath, "Modern Power System Analysis", Tata McGraw Hill, 2014										
e-Lear	e-Learning Source:										

						C	ourse A	Articul	ation N	Aatrix:	(Mappi	ng of COs	s with PO	s and PSO	Os)			
PO- PSO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4	PSO5	PSO6
CO1	2	3	3	3		2							2	2	2			
CO2	2	3	3	3		2							2	3	2			
CO3	1	3	3	3		2							2	2	2			
CO4	1	2	3	3		2							1	2	3			
CO5	2	3	3	3		2							1	3	3			



Effective from Session: 2017	7-18						
Course Code	EE-517	Title of the Course	POWER SYSTEM DYNAMICS & CONTROL	L	Т	Р	С
Year	1 <sup>st</sup>	Semester	1 <sup>st</sup>	4	0	0	4
Pre-Requisite	None	Co-requisite	None				
Course Objectives	<ul> <li>To and</li> <li>To</li> <li>To sys</li> <li>To rea</li> <li>To stal</li> </ul>	understand the students l obtain the solution of tr analyze the modeling of realize and examine the tem. recognize the concepts l time domain. execute the analysis of bility.	about dynamics of Power systems. To develop ability for a ransient problems. f synchronous machine by applying fundamental law's. excitation systems and response the behavior of prime mov of dynamics of synchronous generator Connected to Infini f transient and voltage stability by various parameters an	nalysis ver con te Bus d com	of syst trollers by inve parison	em stab in diffe estigatio with a	ility erent en in ngle

	Course Outcomes
CO1	Given a Power System Dynamics Problems, students shall be able to represent this in various conventional models, identify type of system,
	apply vector algebra, and formulate the expression in different System Model and solve using mathematical terms.
CO2	Given a Modeling of Synchronous Machine with sources, student shall be able to analyze System Simulation and evaluate the Steady State
	Performance using Equivalent Circuit of Synchronous Machine
CO3	For a Excitation systems & Prime Mover Controllers, student shall be able to generate its analytical response by Standard Block Diagram and
	examine, analyze and evaluate the characteristics by State Equations and Load Modeling.
CO4	For Stator Equation, select suitable design of application of Network Equation, develop various combination for System Simulation Small Signal
	and large signal analysis with Block Diagram Representation for Single Machine System,
CO5	Given a Modeling and Analysis of Transient and Voltage Stability, student shall be able to define its Stability Evaluation, solve/ analyze, and
	modify energy functions for direct stability evaluation;

Unit No.	Title of the Unit	Content of Unit	Contact Hrs.	Mapped CO
	Analysis of	Concept of Equilibrium, Small and Large Disturbance Stability, Single Machine Infinite Bus	8	CO1
1	Dynamical	System, Modal Analysis of Linear Systems, Analysis using Numerical Integration		
	Systems	Techniques, Issues in Modelling: Slow and Fast Transients, Stiff Systems.	-	
	Modelling of a	Physical Characteristics, Rotor Position Dependent model, D-Q Transformation, Model with	8	CO2
2	Synchronous	Standard Parameters, Steady State Analysis of Synchronous Machine, and Synchronous		
	Machine	Machine Connected to Infinite Bus.		
	Modelling of	Physical Characteristics and Models, Control system components, Excitation System	8	CO3
2	Excitation and	Controllers, Prime Mover Control Systems.		
3	Prime Mover			
	Systems			
	Modelling of	Transmission Line Physical Characteristics, Transmission Line Modelling, Load Models -	8	CO4
4	Transmission	induction machine model, Other Subsystems - HVDC, protection systems.		
	Lines and Loads			
	Stability Issues in	Single Machine Infinite Bus System, Multi-machine Systems, Stability of Relative Motion.	8	CO5
5	Interconnected	Frequency Stability: Centre of Inertia Motion, Single Machine Load Bus System: Voltage		
	Power Systems	Stability, Torsional Oscillations, Real-Time Simulators.		
Referen	ce Books:			
1. K.R.P	adiyar, Power System I	Dynamics, Stability & Control, 2nd Edition, B.S. Publications, Hyderabad, 2002.		
2. P.Kur	ndur, Power System Stal	pility and Control, McGraw Hill Inc, New York, 1995.		
3. P.Sau	er & M.A.Pai, Power Sy	ystem Dynamics & Stability, Prentice Hall, 1997.		
e-Lear	ning Source:			

						C	ourse A	Articul	ation N	Aatrix:	(Mappi	ng of COs	s with PO	s and PSO	Os)			
PO- PSO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4	PSO5	PSO6
0.	-	-	-								-		-		-			
CO1	3	2	2										3		1			
CO2	3	3	2	2	2								3		3			
CO3	3	3	1											3	2			
CO4	3	2	3	2	3					2	2		2		1			
CO5	3	3	3			2	1							3	2			



Effective from Session: 2017	7-18						
Course Code	EE-518	Title of the Course	Computer Aided Power System Analysis	L	Т	Р	С
Year	1 <sup>st</sup>	Semester	2 <sup>nd</sup>	4	0	0	4
Pre-Requisite	None	Co-requisite	None				
Course Objectives	<ul><li>Det</li><li>Ana</li><li>Fau</li></ul>	ermination of network s alyze load flow using ite lt analysis estimation	ensitivity, trative methods				

	Course Outcomes
CO1	Analysis of power system network in term of matrices
CO2	Load flow analysis using iterative methods
CO3	Analysis of fault under balance and unbalanced condition
CO4	Estimation of the state of the power system using statistical tools
CO5	Analysis of load frequency control for single area and multi area system

Unit No.	Title of the Unit	Content of Unit	Contact Hrs.	Mapped CO						
1	Introduction	Solution of Linear Systems and Contingency Analysis, Matrix representation of power systems, Triangularization, Gaussian elimination, LU and LDU factorization LDLT decomposition for sparse Matrices, Optimal ordering, Overview of Security Analysis, Linear Sensitivity Factors, Contingency Selection, Calculation of Network Sensitivity Factors.	8	CO1						
2	2 Load Flow Analysis Newton–Raphson iteration, Power system applications: Power flow, Formulation of Bus admittance matrix, regulating transformers, Gauss-Seidel, Newton- Raphson and Fast Decoupled methods of power flow, Treatment of voltage-controlled buses, Accelerating factors, DC load flow.									
3	Power flow solutions	Short Circuit Studies, System Representation, Algorithm for formation of bus impedance matrix, Balanced fault, Sequence impedances of power system components, Unbalanced fault Analysis.	8	CO3						
4	Power System State Estimation	Power System State Estimation, Power system state estimator, Method of Least Squares, Statistics, Errors and Estimates, Test for bad data, Network Topology Processing.	8	CO4						
5	Modern control Techniques	Unit Commitment and Load Frequency Control, Constraints in UC, Solution Methods of UC, Automatic Load Frequency Control of Single Area System and Multi Area System, Steady State Instabilities.	8	CO5						
Referen	ce Books:									
1. Hadi S	Saadat, "Power System	Analysis", Tata Mc Graw Hill, 2003.								
2. A. J. V	Wood and B.F.Wollenbe	erg, "Power Generation Operation and Control", John Wiley & Sons, ICN., 2nd Edition.								
3. A. K.I "Power S	Mahalanabis, "Compute System Analysis", McG	r Aided Power system analysis and control", Tata McGraw Hill 1991 4. John J. Grainger, Willia raw Hill, 1994.	m D. Steven	son, JR.						
5. Elgere	l olleI, "Electric Energy	Sytems Theory- An Introduction", Tata Mc Graw Hill, 2ed. 1995.								
6. I. J. Nagrath & D.P. Kothari, "Modern Power System Analysis", Tata McGraw Hill, 1989										
7.Wadhy	wa C L, "Electrical Pow	er Systems", New Age Publication, 3ed., 2002								
. I com	•									

e-Learning Source:

						С	ourse A	Articul	ation N	Aatrix:	(Mappiı	ng of COs	s with PO	s and PSO	Ds)			
PO- PSO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4	PSO5	PSO6
C01	1	2	3										2	3	1			
CO2		3	2										2	3	2			
CO3	2	3	2										3	2	2			
CO4	2	3	2										3	2	3			
CO5	2	2	2										2	2	2			



Effective from Session: 2017	7-18						
Course Code	EE-519	Title of the Course	ADVANCE RELAYING AND PROTECTION	L	Т	Р	С
Year	1 <sup>st</sup>	Semester	2 <sup>nd</sup>	4	0	0	4
Pre-Requisite	None	Co-requisite	None				
Course Objectives	• Apj	ply the knowledge of rel	ays in power system protection				

	Course Outcomes
CO1	To learn the basics of relays
CO2	Knowledge of relay applications
CO3	Knowledge of protection of generator, motors and transformers
CO4	Study of different types of system grounding, faults and protection
CO5	Knowledge of digital relays

Unit No.	Title of the Unit	Content of Unit	Contact Hrs.	Mapped CO							
1	Protective Relaying	Relay terminology, Definitions, Classification, electromechanical, static and digital-numerical relays. Design-factors affecting performance of a protection scheme; faults-types and evaluation, Instrument transformers for protection.	8	CO1							
2	8	CO2									
Protection of 3       Generator, Transformer, Transmission Systems, Busbars, Motors; Pilotwire and Carrier Equipments       8       CO3											
4	System Grounding	Ground faults and protection; Load shedding and frequency relaying; Out of step relaying; Re-closing and synchronizing.	8	CO4							
5         Basic Elements Of Digital Protection         Digital signal processing, Digital filtering in protection relay, Digital Data transmission, Numeric relay hardware, relay algorithm, distance relays, direction comparison relays, differential relays, software considerations, numeric relay testing.         8											
Referen	ce Books:										
1. A T Jo	ohn and A K Salman-Di	gital protection for power systems-IEEE power series-15, Peter Peregrines Ltd, UK,1997									
2. C.R. N	Mason, The art and scien	nce of protective relaying, John Wiley &sons, 2002									
3. Donal	d Reimert, Protective re	laying for power generation systems, Taylor & Francis-CRC press 2006									
4. Gerha	rd Ziegler-Numerical di	stance protection, Siemens, 2nd ed, 2006									
5. A.R.V	Varrington, Protective R	elays, Vol .1&2, Chapman and Hall, 1973									
6. T S.M	ladhav Rao, Power syste	em protection static relays with microprocessor applications, Tata McGraw Hill, 1994									
7. Helmut Ungrad, Wilibald Winkler, Andrzej Wiszniewski, Protection techniques in electrical energy systems, Marce Dekker, Inc. 1995											
8. Badri	Ram, D.N. Vishwakarı	na, Power system protection and switch gear, Tata McGraw Hill, 2001.									
_											

e-Learning Source:

						C	ourse A	Articul	ation N	Aatrix:	(Mappi	ng of COs	s with PO	s and PS	Os)			
PO- PSO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4	PSO5	PSO6
CO1	3			1									1	2	1			
CO2	3	2		1									2	1	1			
CO3	3	1			1								1	2	2			
CO4	3	1		2									2	1	3			
CO5	3	1	2		1								3	1	1			



Effective from Session: 2017	Effective from Session: 2017-18											
Course Code	EE-520	Title of the Course	ADVANCE RELAYING AND PROTECTION	L	Т	Р	С					
Year	1 <sup>st</sup>	Semester	2 <sup>nd</sup>	4	0	0	4					
Pre-Requisite	None	Co-requisite	None									
Course Objectives	To     Con     To     sysi     To     pov     opt	provide students the kn htrol (LFC) provide a solid foundati tem in Turbine models. provide the knowledge ver generation operation imal power flow problem	owledge of optimization techniques used in the power syst ion in mathematical and engineering fundamentals required of Hydrothermal scheduling, reactive power control,basic n and control, review of optimization, economic dispatch p ms, and their solution methods.	em an to cor objec proble	d Load ntrol the tive of ns, for	Freque govern security nulatior	ncy iing y in 1 of					

	Course Outcomes
CO1	Optimization, network and economic analysis of power system network.
CO2	Analyze and implement the power flow problem and its solution. Introduce the coordination equations, incremental losses, and penalty factors.
CO3	Understand the constraints in unit commitment and implementation these constraints for solving the different solution methods for unit
	commitment problem.
CO4	Understand, analyze hydro generator coordination problem and generation rescheduling
CO5	Knowledge of modern power system and the factors needed for updation

Unit No.	Title of the Unit	Content of Unit	Contact Hrs.	Mapped CO
1	Introduction	Characteristics of power generation units(thermal, nuclear, hydro, pumped hydro), variation in thermal unit characteristics with multiple valves, Economic dispatch with and without line losses, lambda iteration method, gradient method, Newton's method, base point and participation factor	8	CO1
2	Transmission losses	Co-ordination equations, incremental losses, penalty factors, B matrix loss formula (without derivation), methods of calculating penalty factors.	8	CO2
3	Unit commitment	Constraints in unit commitment, priority list method, Dynamic programming method and Lagrange relaxation methods. Generation with limited energy supply, take or pay fuel supply contract, composite generation production cost function, gradient search techniques.	8	CO3
4	Hydrothermal co- ordination:	Scheduling energy, short term hydrothermal scheduling, lambda-gamma iteration method, gradient method, cascaded hydro plants, pumped storage hydro scheduling.	8	CO4
5	Optimal power flow formulation	Gradient and Newton method, linear programming methods. Automatic voltage regulator, load frequency control, single area system, multi-area system, tie line control.	8	CO5
Referen	ce Books:			
1. Allen	J. Wood and Bruce F.	Wollenberg, 'Power Generation, Operation and Control', John Wiley & Sons, Inc., 2003.		
2. Olle.I	Elgerd, 'Electric Energ.	y Systems theory – An introduction', Tata McGraw Hill Education Pvt. Ltd., New Delhi, 34th re	print, 2010.	
3. Abhij	it Chakrabarti, Sunita H	alder, 'Power System Analysis Operation and Control', PHI learning Pvt. Ltd., New Delhi, Third	d Edition, 20	)10.
4. Abhij	it Chakrabarti, Sunita H	alder, 'Power System Analysis Operation and Control', PHI learning Pvt. Ltd., New Delhi, Third	d Edition, 20	)10.
5. N.V.F	amana, "Power System	Operation and Control," Pearson, 2011.		

e-Learning Source:

	Course Articulation Matrix: (Mapping of COs with POs and PSOs)																	
PO- PSO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4	PSO5	PSO6
CO1	3	2	3	3	2	3	2		2		2		3	2	1			
CO2	3	1	3	1	2	1			1		1		1	2	1			
CO3	3	2	3	3	2	1	2		1	1	2		3	2	2			
CO4	3	1	3	2	2	1			1	1			2	2	1			
CO5	3	2	2	2	3	2	2	1	2	2			3	2	2			



Effective from Session: 2017-18											
Course Code	EE-521	-521 Title of the Course High Voltage Testing Techniques L									
Year	1 <sup>st</sup>	Semester	2 <sup>nd</sup>	4	0	0	4				
Pre-Requisite	None	Co-requisite	None								
Course Objectives	• Kn	owledge of different typ	es of HV testing methods used in testing electrical equipme	nt's							

	Course Outcomes								
CO1	Determination of switching surges using impulse testing on generators								
CO2	Determination of voltage time characteristics for different specimens								
CO3	Determination of voltage time characteristics for insulators, bushings etc.								
CO4	Analyze the results of impulse and p.f. tests on dielectrics								
CO5	Analyze the transformers, capacitors and cables with different types of HV tests								

Unit No.	Title of the Unit	Content of Unit	Contact Hrs.	Mapped CO
1	Generation of High Voltages and Currents	Need and importance of impulse testing. Study of impulse voltage and current generators Generators for Lightning and Switching Impulse Voltages, Chopped Impulse Voltages, Steep- Front Impulse Voltages, Exponential Impulse Currents, Rectangular Impulse Currents.	8	CO1
2	Volt-time characteristics I	Method of wave shaping and oscillographic measurement; Volt-time characteristics of rod-rod, sphere-sphere, rod-plane gaps.	8	CO2
3	Volt-time characteristics II	Volt-time characteristics of insulators, bushings, gaps of positive and negative polarity, horn gap, rod gap, lightning arresters – expulsion type, valve type.	8	CO3
4	Testing Techniques I	Current testing of lightning arresters – Long duration impulse current test, Operating Duty Cycle Test; Testing of dielectrics – Power frequency tests, Impulse tests; Applications of insulating materials.	8	CO4
5	Testing Techniques II	Testing of transformers – Induced over voltage test, Partial discharge test, Impulse test; Testing of Capacitors; Testing of Cables - Dielectric Power Factor Test, High Voltage Tests, Partial discharge measurement.	8	CO5
Referen	ce Books:			
1. M.S. 1	Naidu & V. Kamaraju, ''	High Voltage Engineering", McGraw-Hill, 2014		
2. C.L. V	Wadhwa, "High Voltage	Engineering", New Age International Publishers, 2014		
3. Subir	Ray, "An Introduction t	o High Voltage Engineering", Prentice Hall of India, 2004.		
e-Lear	ning Source:			

#### Course Articulation Matrix: (Mapping of COs with POs and PSOs) PO-PSO CO PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PSO1 PSO2 PSO3 PSO4 PSO5 PSO6 2 2 2 3 1 1 CO1 2 2 3 1 1 1 CO2 2 2 1 1 1 3 CO3 2 2 3 1 1 1 CO4 3 2 3 1 1 1 CO5



Effective from Session: 2017-18											
Course Code	EE-522	Title of the Course	High Voltage Testing Techniques	L	Т	Р	С				
Year	1 <sup>st</sup>	Semester	2 <sup>nd</sup>	4	0	0	4				
Pre-Requisite	None	Co-requisite	None								
Course Objectives	• Kno	owledge of different typ	es of HV testing methods used in testing electrical equipment	nt's							

	Course Outcomes								
CO1	Knowledge of different types of power system stability								
CO2	To get knowledge of energy function								
CO3	To attain knowledge of modelling of machines								
CO4	To study about power system stabilizer								
CO5	To have the knowledge of voltage stability								

Unit No.	Title of the Unit	Content of Unit	Contact Hrs.	Mapped CO
1	Power System	States of operation, Basic concepts of angular and voltage stability. Angular stability: Analysis	8	CO1
1	Stability	of single machine and multi-machine systems for transient stability.		
2	Energy function	Digital simulation and energy function methods. Energy function analysis of single machine	8	CO2
	Energy function	system. Small signal stability (dynamic stability)		
2	Modeling of	Modeling for single machine and multi-machine systems, Synchronizing and damping torque	8	CO3
3	machines	analysis, Eigen value and time domain analysis.		
4	Power System	Mitigation using power system stabilizer and FACTS controllers. Basic concepts in applying	8	CO4
4	Stabilizer (PSS)	PSS, Control Signals, Structure and tuning of PSS Introduction to sub synchronous resonance.		
-	<b>X7 - 14 1 - 11 * 11 * 4</b>	Power-Voltage (P-V) and Reactive Power-Voltage (Q-V) curves, static analysis, sensitivity	8	CO5
5	voltage stability	and continuation method. Dynamic analysis.		
Referen	ce Books:			
<b>1.</b> P. Ku	ndur Power System Stal	pility and Control, Mc - Graw Hill .		
<b>2.</b> K. R.	Padiyar Power System	Dynamics, Stability & Control, Interline Publishers, Bangalore		
3. P. Sau	ar and M. A. Pai Power	System Dynamics & Stability, Prentice Hall		
<b>4.</b> G.W.	Stagg & A.H. Al Abiad	Computer Methods in Power System, Mc - Graw Hill		
e-Lear	ning Source:			

	Course Articulation Matrix: (Mapping of COs with POs and PSOs)																	
PO- PSO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4	PSO5	PSO6
CO1	3	1	1	1	1	1	1				3			2	2			
CO2	3	3	3	2	2	1					3		1	2				
CO3	3	2	2	2	2	1					3		2	3				
CO4	3	1	1	1	1	1	1				3			2	3			
CO5	3	1	1	1	1	1	1				3			2				



Effective from Session: 2017-18											
Course Code	EE-523	Title of the Course	Course         Advance Electric Drives								
Year	1 <sup>st</sup>	Semester	2 <sup>nd</sup>	4	0	0	4				
Pre-Requisite	None	Co-requisite	None								
Course Objectives	<ul> <li>Kno</li> <li>Eva</li> <li>Mo</li> </ul>	owledge of AC and DC duate performance of d delling of drives using s	drives rives software								

	Course Outcomes									
CO1	Analyze the motoring and braking operation in drives									
CO2	Control the motors using different methods									
CO3	Mathematical modelling of different drives topologies									
CO4	Analyze the drives under unbalanced condition									
CO5	Analyze different types of SM drives									

Unit No.	Title of the Unit	Content of Unit	Contact Hrs.	Mapped CO
1	DC Motor Drive	Characteristics of different dc motors: their speed control and braking operations: Converter fed dc motor drives: Analysis for motoring and braking operations. Dynamic modelling of dc motor drives; Closed-loop control; Dual converter fed dc motor drives.	8	CO1
2	Induction Motor Drive I	8	CO2	
3	Induction Motor Drive II	Field Oriented Control of IM: configurations, mathematical modelling. VSI- and CSI- based schemes, Slip-power recovery schemes: static Scherbius and Kramer drives, Doubly-fed IM drive.	8	CO3
4	Synchronous Motor Drives I	8	CO4	
5	Synchronous motor drives II	8	CO5	
Referen	ce Books:			
1. "Powe	er Electronics and Moto	r Drives – Advances and Trends" IEEE Press, 2006 by B.K. Bose.		
2. "Powe	er S.C.drives" Prentice-	Hall 1989 by G.K. Dubey.		
3. "Elect	tric Motor Drives", , Mo	odeling, Analysis and Control", Prentice Hall of India, 2002 by R. Krishnan		
4. "High	Power Converters and	AC Drives"IEEE Press, A John Wiley and Sons, Inc., 2006 by Bin Wu.		
e-Lear	ning Source:			

	Course Articulation Matrix: (Mapping of COs with POs and PSOs)																	
PO- PSO CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4	PSO5	PSO6
CO1	3	3	3										1	3	2			
CO2	3	2	2										1	2	3			
CO3	3	3	2										2	3	3			
CO4	2	2	2												2			
CO5	2	2	3										2					



Effective from Session: 2017-18												
Course Code	EE524	Title of the Course	Course         Advance Power Electronics Lab									
Year	Ι	Semester	П	0	0	2	1					
Pre-Requisite		Co-requisite										
Course Objectives	<ul> <li>To</li> <li>To</li> <li>To</li> <li>To</li> <li>To</li> </ul>	understand and experim understand the working understand the DC Con understand the use of si understand the applicati	ent with the Phase control of SCR using RC triggers circuit of SMPS and its output characteristics verters and dual converters ngle phase converter. on of VSI in three phase machines.									

	Course Outcomes
CO1	Adopt, perform, analyze the use of Phase control of SCR using RC triggers circuit
CO2	Adopt, perform, analyze the working of SMPS and its output characteristics
CO3	Adopt, perform, analyze the DC Converters and dual converters
CO4	Adopt, perform, analyze the use of single phase converter.
CO5	Adopt, perform, analyze the application of VSI in three phase machines.

Exp. No.	Title of the Unit	Content of Experiment	Contact Hrs.	Mapped CO				
1		To study the Phase control of SCR using RC triggers circuit	2	1				
2		2	2					
3	3 To study the speed control of single phase dual converter							
	To obtain the output of chopper (step-down) based on DC shunt motor Drive using SIMULINK							
4		2	4					
5		To study speed control of 1- phase induction motor using single phase AC voltage converter	2	4				
6		Obtain the output of half wave converter (single phase) based on DC shunt motor Drive using SIMULINK	2	4				
7		To study the speed control of three phase squirrel cage induction motor using VSI	2	5				
Referen	ce Books:							
1. Ned N	Iohan, Tore M, Undelna	ad, William P, Robbins (3rd Edition), "Power Electronics: Converters, Applications and Design,"	" Wiley 2002	2.				
2. L. Un	nanand, Power Electroni	cs - Essentials and Applications; Wiley India Pvt. Ltd, Reprint Edithion, 2014						
3. P.C Se	en.,' Modern Power Ele	ctronics ', Wheeler publishing Co, First Edition, New Delhi, 1998.						
4. M H F	Rashid, Power Electroni	cs - Circuits, Devices and Applications; PHI, New Delhi, 3rd Edition, 2004						
e-Lear	ning Source:							

PO-PSO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	POS	PO9	PO10	PO11	PSO1	PSO2	PSO3	
CO	101	101	102	105	104	105	100	107	100	10)	1010	1011	1501	1502	1505
CO1	3	3	1	2	3						3	2	2	3	
CO2	3	3	1	2	3						1	2		3	
CO3	3	1	1		3						2	2		1	
CO4	3	2	2		3						1	2	3	1	
CO5	3										3	3		2	